

Initiate Programming

- **Power up (AC) one motor at a time.** Select the transmitter/channel you want to use. Press and hold both the **UP** and **DOWN** buttons *simultaneously* until the motor *jogs*, then release. (A jog is a short up and down movement of the motor)

Check/Change the Direction

- **Check** the direction of operation (the motor will operate in momentary fashion).
- Confirm that the **UP** button brings the application up or in.
- To **change** the direction, press the **STOP** button for more than 5 seconds until the motor jogs, then release.
- Check the direction.

Setting the Limits/User Mode

- Start at an upper reference point (upper limit). Press both the **STOP** and **DOWN** buttons *simultaneously* until the motor begins to rotate, then release.
- Stop the motor where you want to set the lower limit. Adjust if necessary by pressing the **UP** or **DOWN** buttons.
- Press and hold both the **STOP** and **UP** buttons simultaneously until the motor rotates **UP**, then release. Stop the motor where you want to set the upper limit (or it will stop automatically at the initial upper reference point). Adjust if necessary. Press the **STOP** button for 5 seconds until the motor jogs. The limits are now recorded. (**INSTALLER MODE**)
- **User Mode:** Press the program button for 3 seconds, until the motor jogs, to record the transmitter for user mode (the motor operates in maintained fashion).

Add/Delete a Transmitter/Channel

- To **ADD** a transmitter/channel, press the programming button on an already recorded one until the motor jogs. Select the transmitter/channel to add and press its programming button until it jogs, then release.
- To **DELETE** a transmitter/channel, press the programming button on an already recorded one until the motor jogs. Select the transmitter/channel to delete and press its programming button until it jogs, then release.

Setting the Intermediate Position

- Once the limits are set, the motor is in USER MODE. Operate the motor to the location you would like as your intermediate position with an already programmed transmitter/channel and press the **STOP** button. Release and press the **STOP** button again for 5 seconds until the motor jogs, then release. Check it. (To use access the intermediate position, press the **stop** button